

## IEAMNASA

Jessa Hafer-Zdral document lead Joanna Bresee design lead

Steve Hillenius technical lead Jon Bidwell user research lead M. Azim Ali project manager



#### project advisors

#### **Ames HCI Group**

Alonso Vera Mike McCurdy Mel Ludowise

#### **Intelligent Robotics Group**

Terry Fong
Trey Smith
David Lees



#### presentation outline

- 1. background
- 2. project focus
- 3. research methods
- 4. findings
- 5. design implications
- 6. project timeline
- 7. brainstorming



#### our project focus

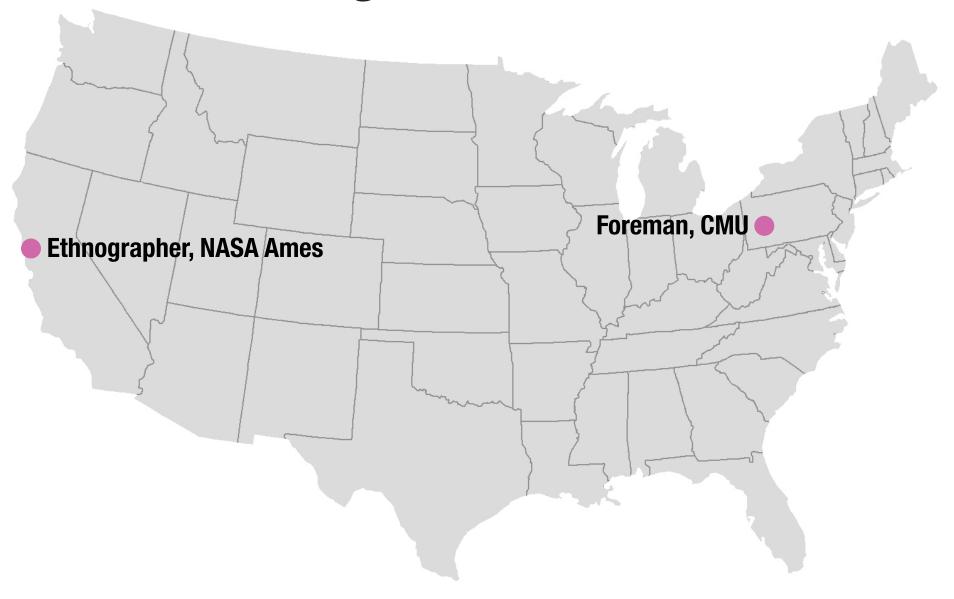
Design a planning tool to improve the speed in which scientists analyze data and plan robotic recon activities



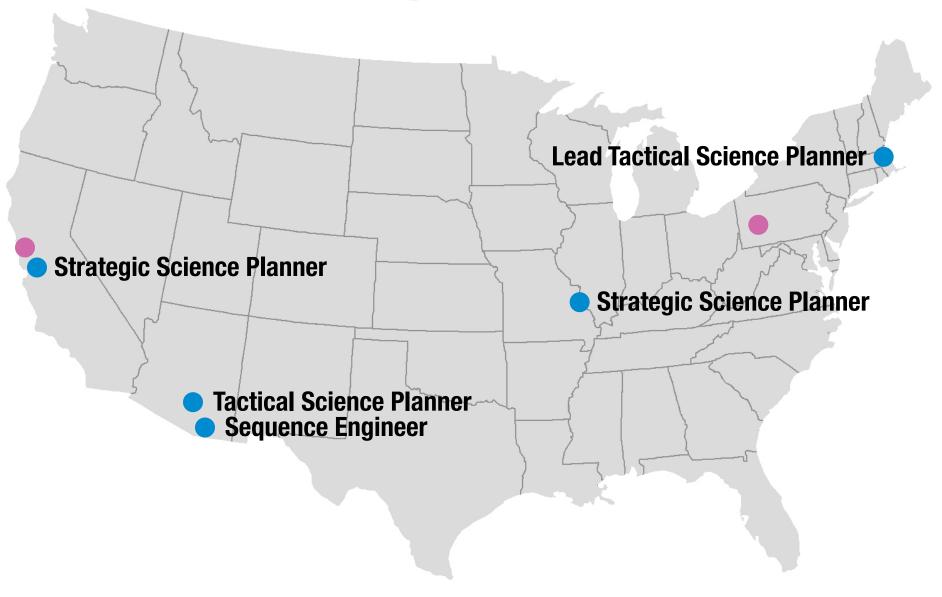
#### research process



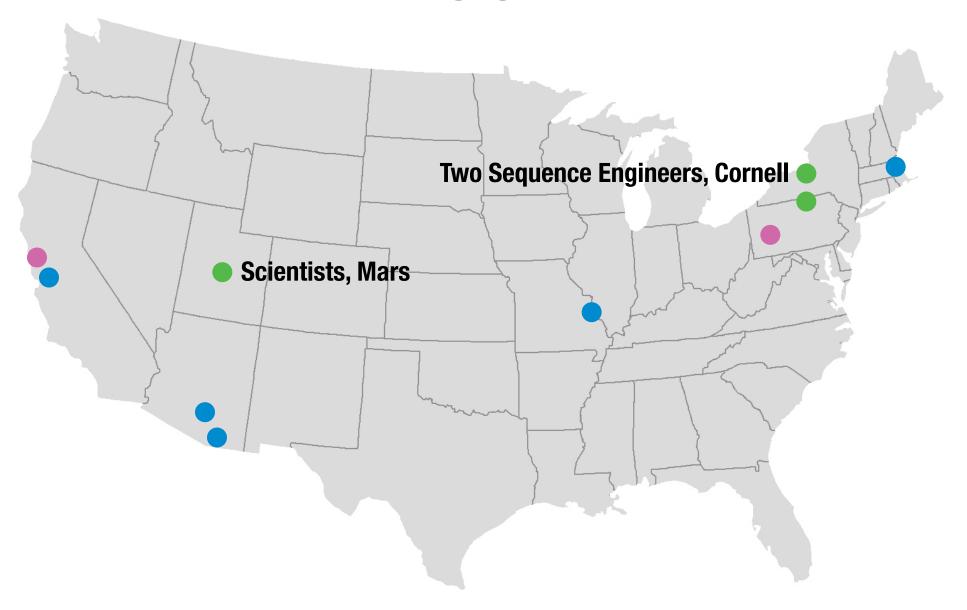
#### analogous interviews



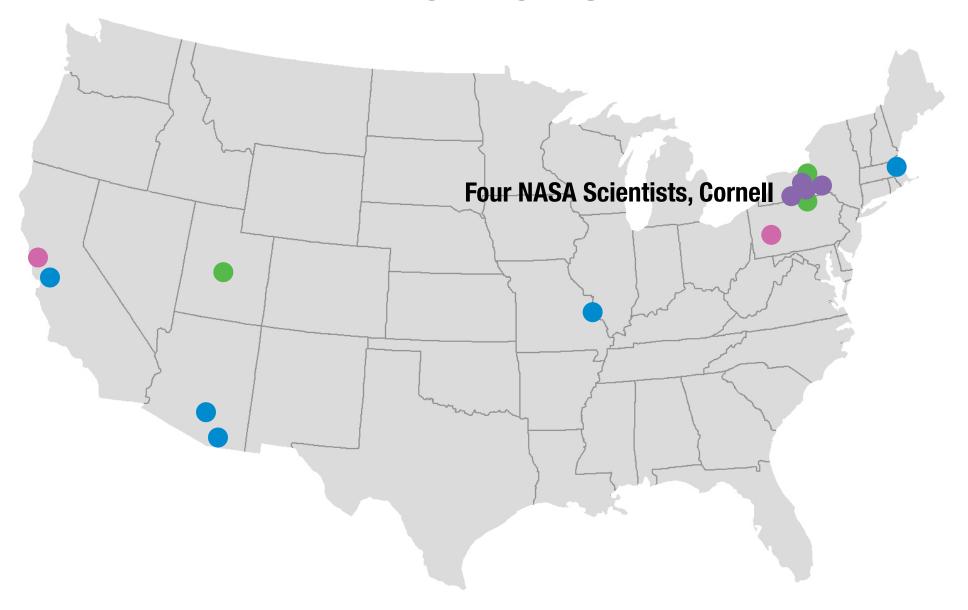
#### retrospective CIs



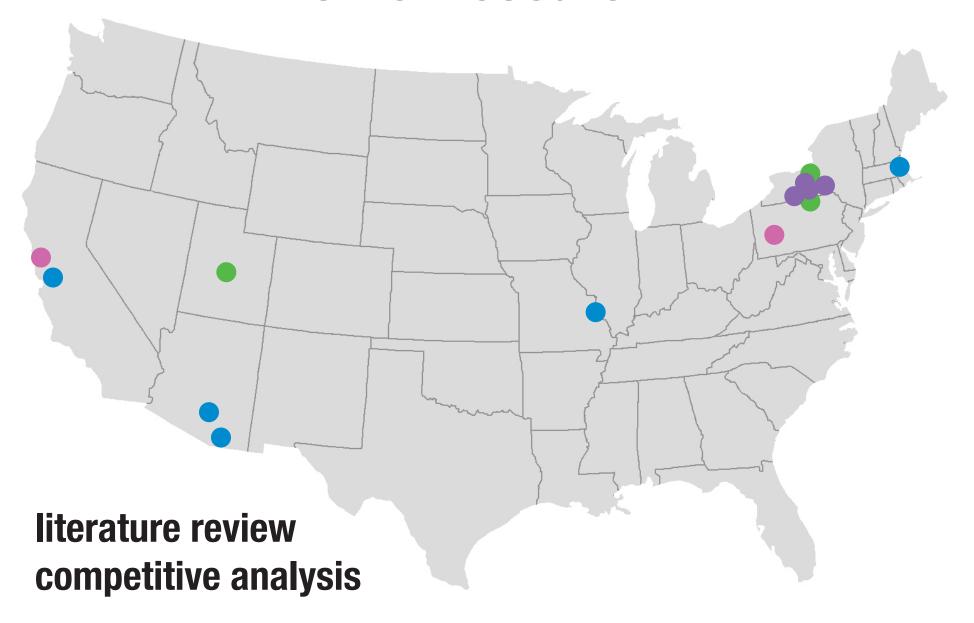
#### CIS



#### interviews



#### other research



#### modeling and consolidation



#### machine shop foreman



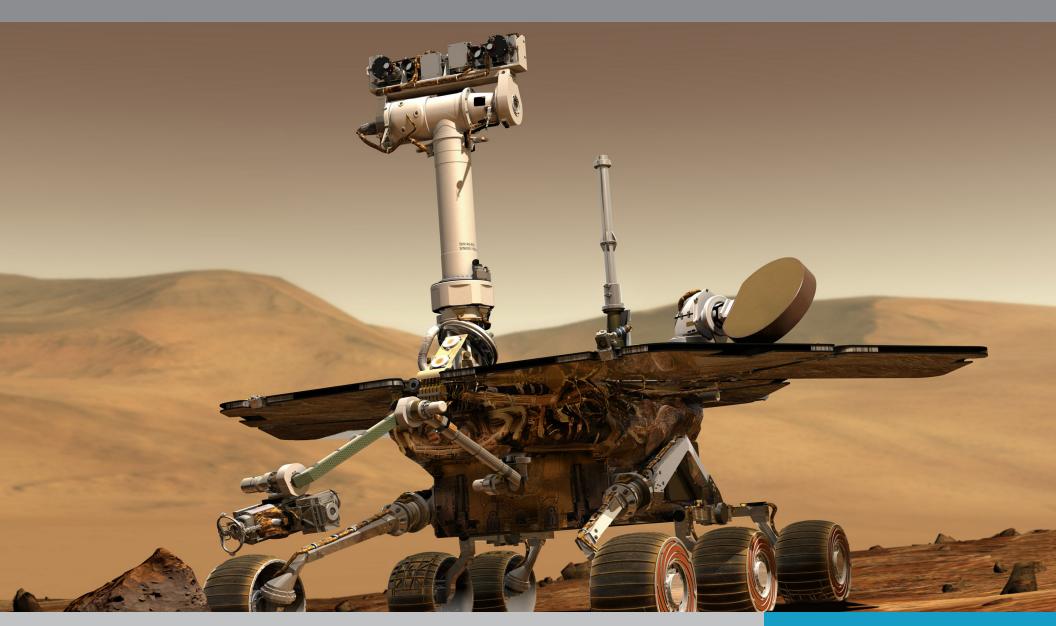
#### international space station



#### mars desert research station



#### mars exploration rover



#### phoenix lander

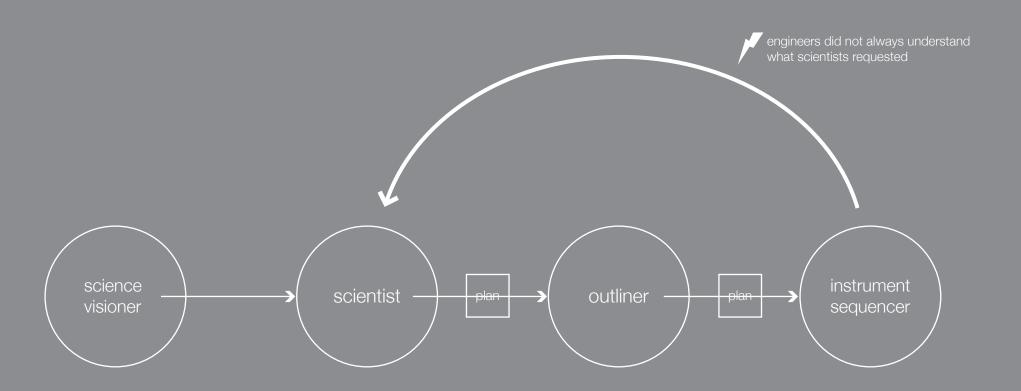


#### themes

- 1. Scientists were not able to communicate in a language engineers could use
- 2. Ongoing local problem solving required immediate communication
- 3. Specialized tools created fragmented planning workflow



# theme 1: scientists were not able to communicate in a language engineers could use



understanding constraints

### 1

## "Scientists think everything is possible all the time."

-Phoenix Instrument Sequence Engineer

tension between roles

"I'd like to say that everyone was competent, but that's just not the case sometimes."

-Phoenix Instrument Sequence Engineer

difficulty planning

# "They knew that they [expletive deleted] at PSI, and they would tell us that."

-Phoenix Tactical SPI

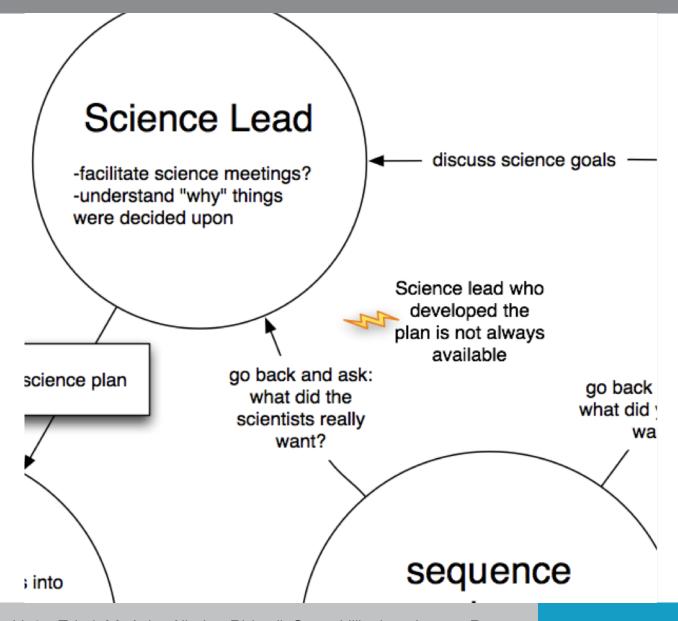
constraints not communicated

1

"How long it takes to turn an instrument on would constantly change and that information didn't get out to all forty people that could be building a plan."

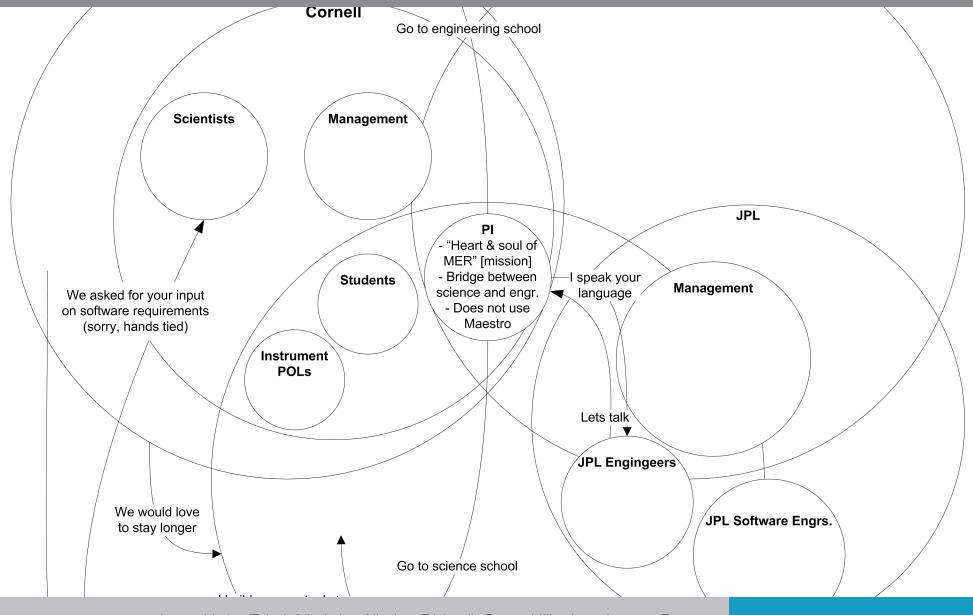
-Phoenix Tactical SPI

#### hard to understand intent



cross training





hard to understand intent

1

"Do the students' requests get better over time?"

"Absolutely."

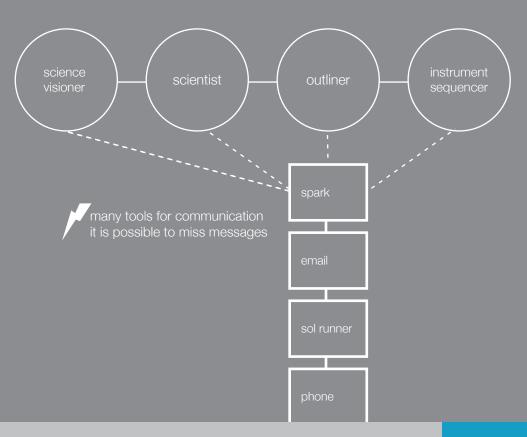
-CMU machine shop foreman

1

design implication:
visualize constraint information in a way
that is easy for scientists to understand

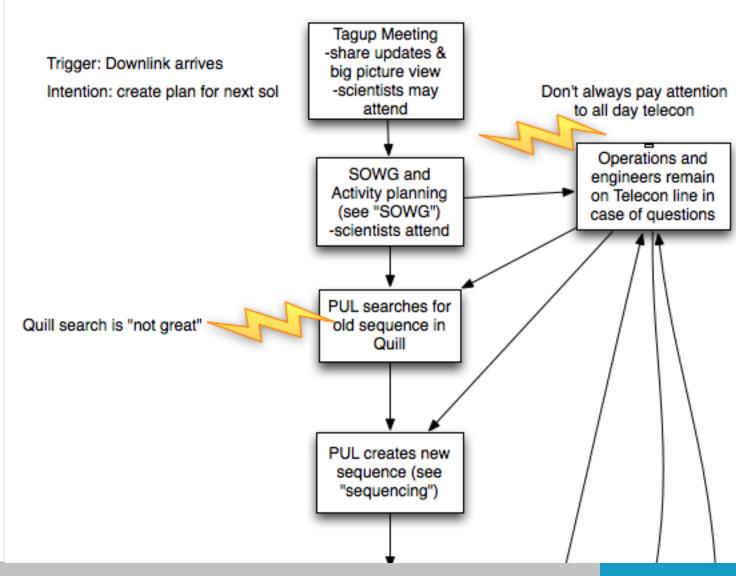
theme 2:

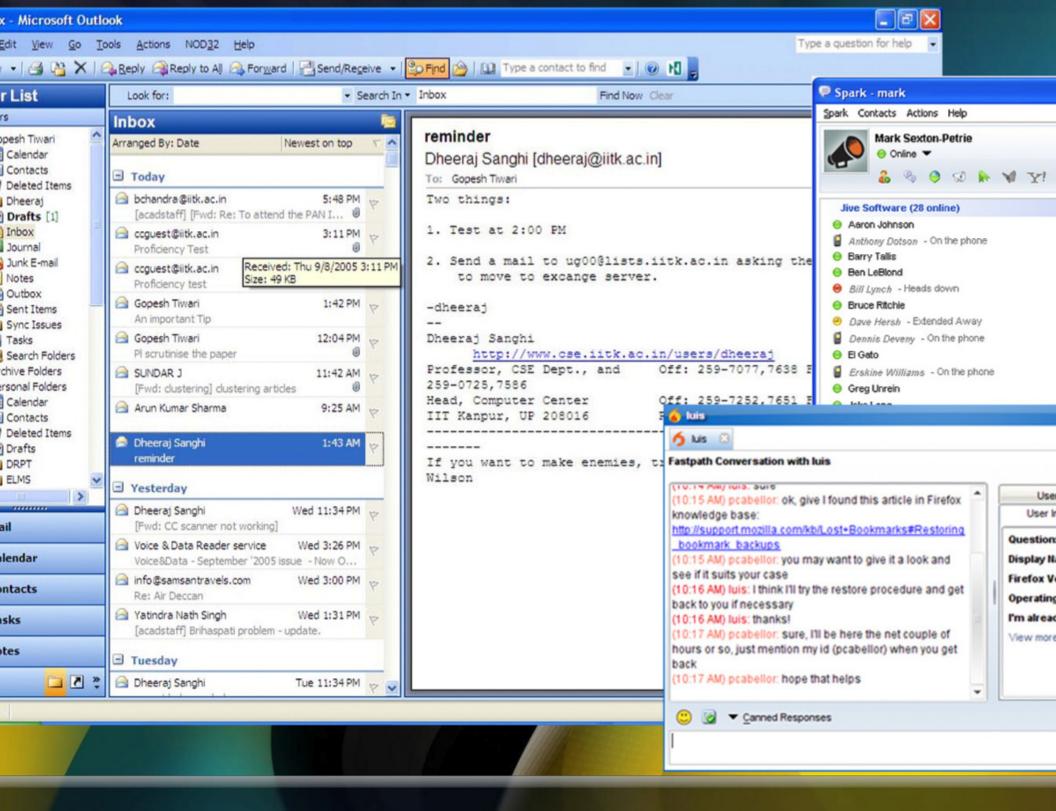
### ongoing local problem solving required immediate communication



"It was frustrating because you knew there was someone who could answer your question right away, but they weren't available."

-Phoenix Instrument Sequence Engineer



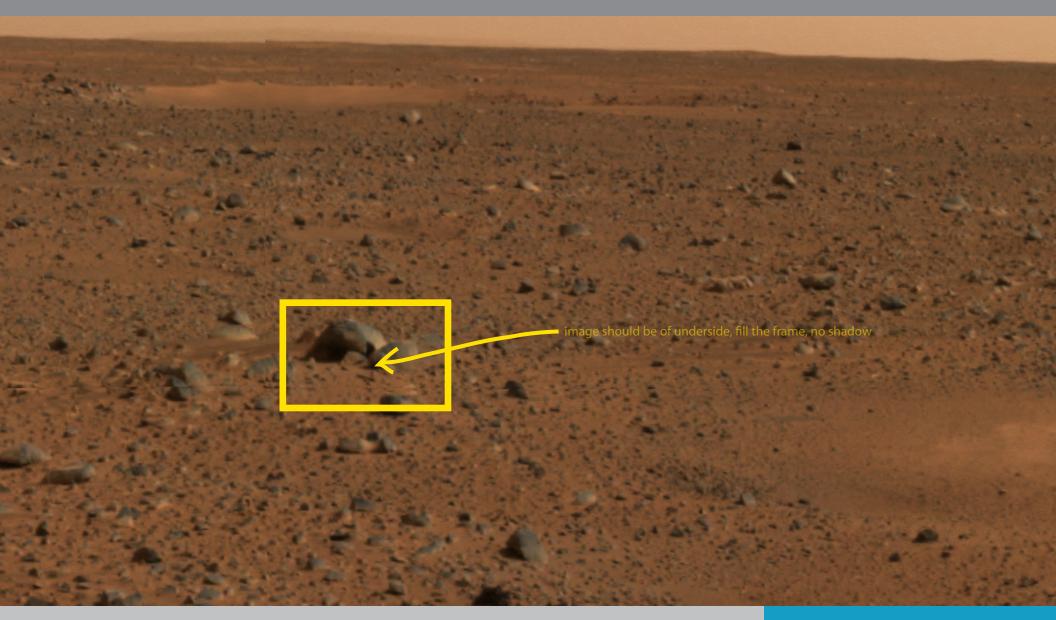


# "You don't have time to look in twenty different places to find out if you've been communicated with."

-Phoenix Lead Tactical SPI

## "Visuals helped a lot when they were there."

-Phoenix Lead Tactical SPI

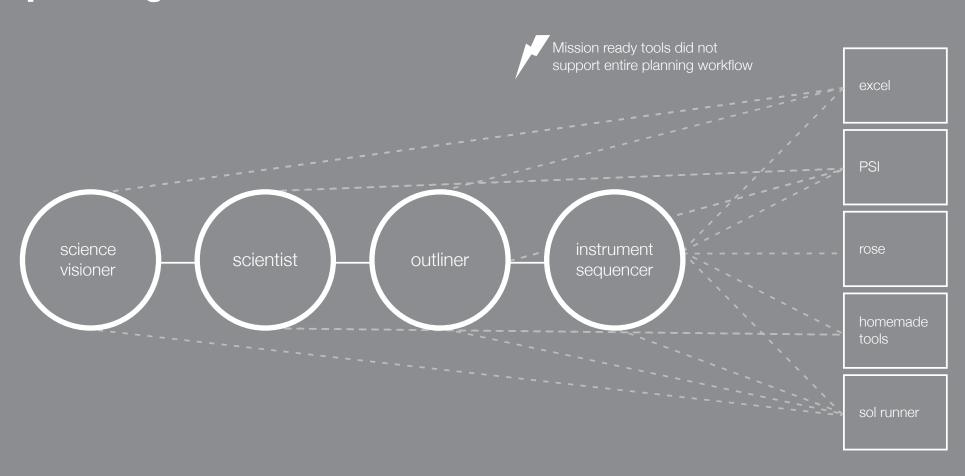


# design implication: incorporate communication tools within planning for rapid troubleshooting

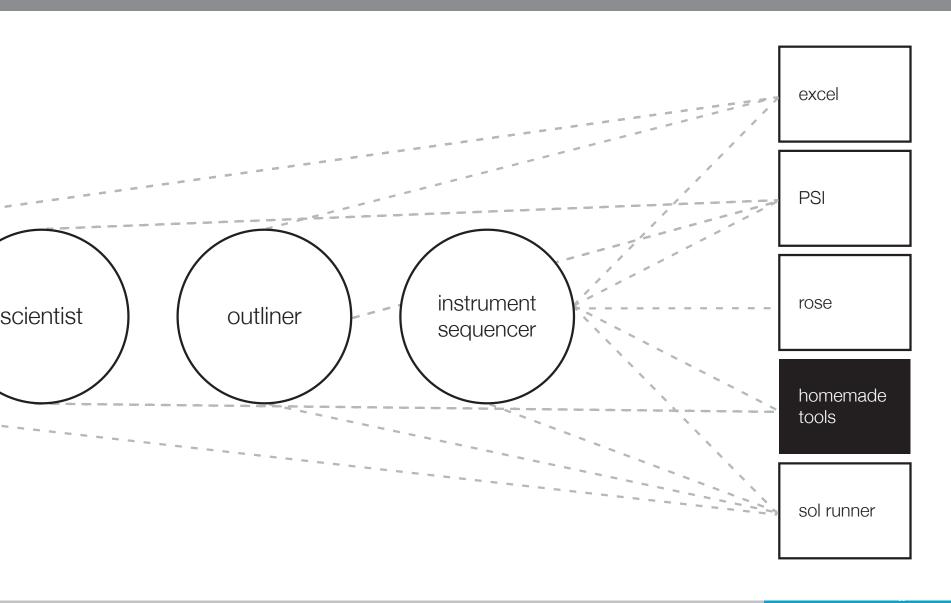
theme 3:

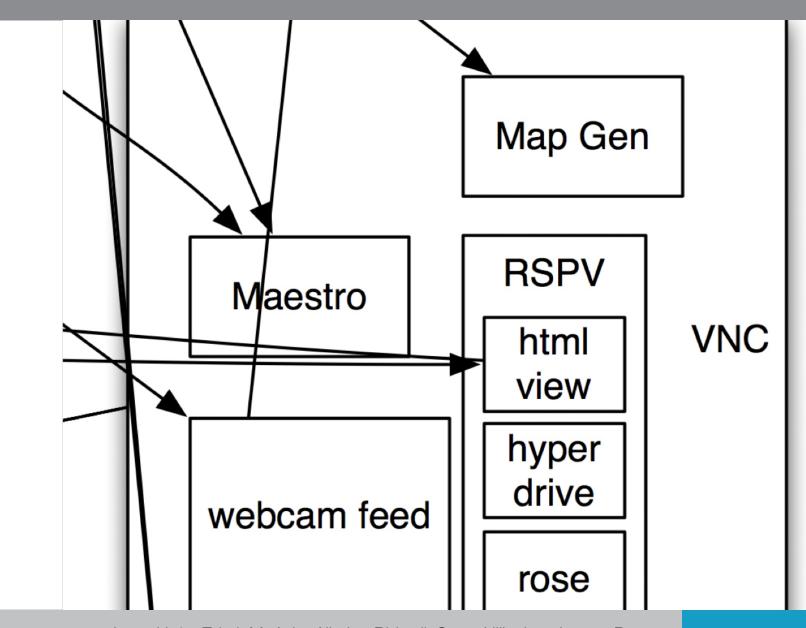
## 3

### specialized tools created fragmented planning workflow



homemade tools





generic tools

Planning day				PRIMARY MISSION		
lanning day of the week		Sol 58	Sol 59	Sol 60	Sol 61	Sol 62
ns due to SSP by AM of:						
Restricted Power						
Interaction Limit (ISEs)						
Sampling Interop .	Scraping at SnowWhite, B2F Maneuver, TEGA and WCL0 del pose	RA Placement Test, Scraping in Snow White	RA down day, B2F Xfer and dump	4x4 RASP, acquire sample and delivery to TEGA	Sprinkle sample on MECA cover	Scrape, RASF Acquire and Deli sample to TEG
Surface Imaging .		Photometry	Change Monitoring DodoGoldi, photom, Happy pan	Coordinated HiRISE		Change monitori (DodoGoldi)
RAC .	Doc clean scoop and divot		Image scoop			

#### no standardization



#### RA IDE [Edit]

Summary. - - 2008-06-26 01:32:59 GMT Last Updated: - 2008-06-26 04:34:58 GMT

#### General overview

Tosols RA activities consisted of delivering a sample to WCL0, a first time activity. Post deliver then moved to the acquire sample site and a RAC image taken. The scoop was then moved to the ws followed by RA actuator characterization at an azimuth pose p from the sol 4 run of the same

#### SSP - Strategic Sci Planr [Edit]

Summary Last Updated:	- 2008-07-09 13:20:34 GMT - 2008-07-09 13:22:02 GMT
PLAN:	
strategic_sol45_p	rimary_v1
APF:	

design implication:
enable planning tools to evolve with the mission

#### robotic recon

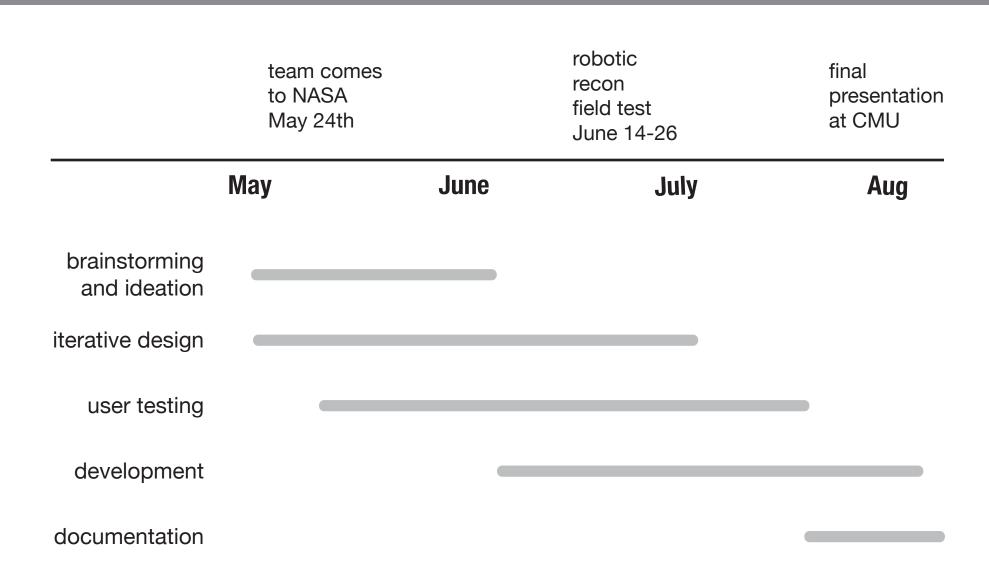
- 1. Advance field survey
- 2. Surface data vs. orbital data
- 3. Maximize crew productivity

# findings

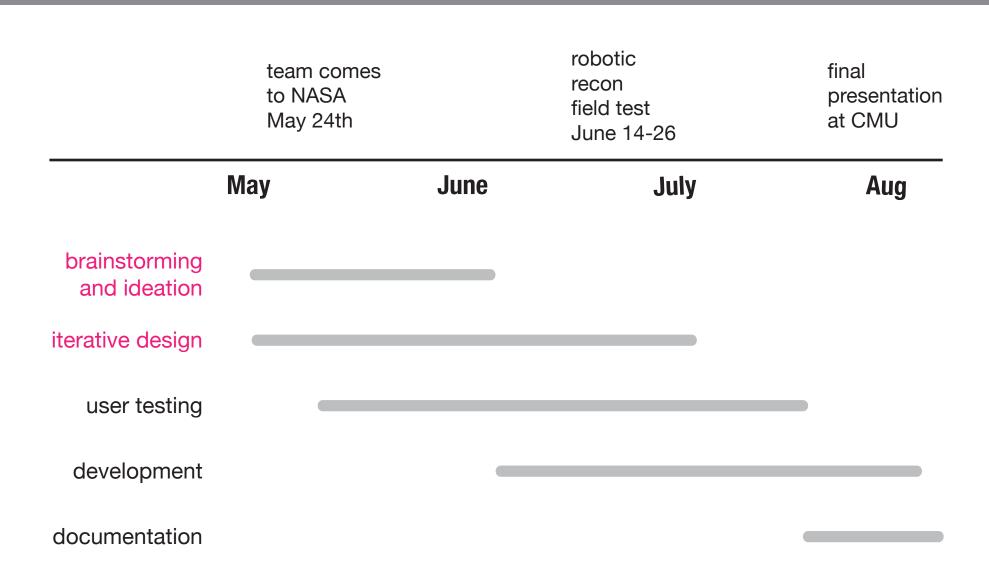
primary bottleneck is science operations

"There are competing pressures to analyze new data vs. generate next plans."

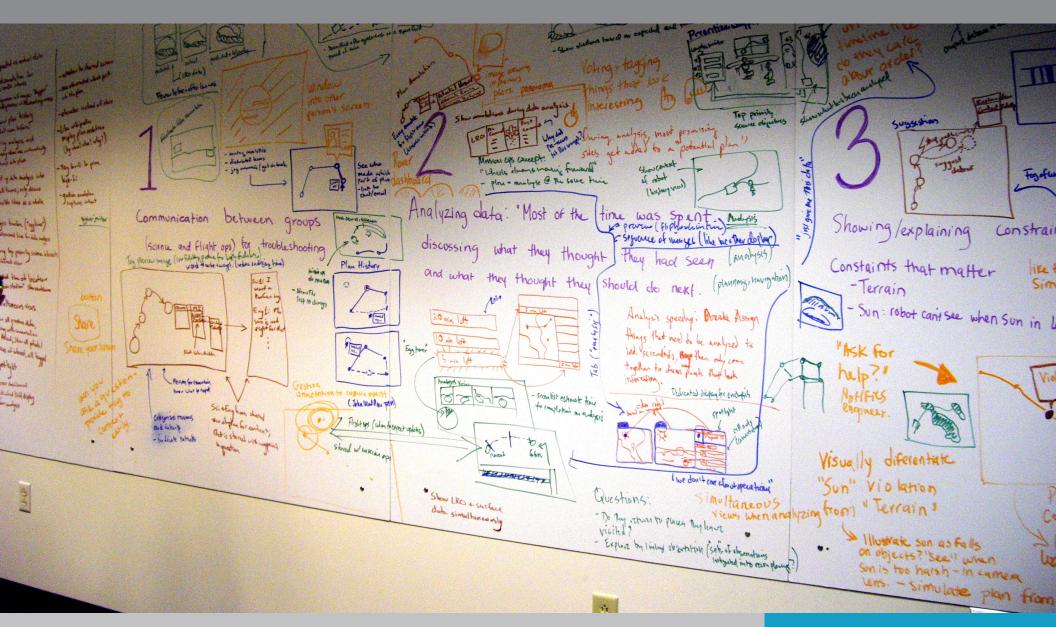
### project timeline



### project timeline



# brainstorming



## design directions

- 1. support communication between groups for troubleshooting
- 2. create a tool to help speed up data analysis
- 3. explain constraint information in a way that scientists can understand

